Toric varieties from cyclic matrix groups

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The motivation

- Polynomial equations provide the strongest algebraic invariants.
- Membership problem: is $x \in X$? If $x \notin \overline{X}$, then $x \notin X$.
- Dynamical systems (= automata, affine programs). <u>Theorem</u>: \overline{X} is computable.
 - X ⊆ GL_n(ℂ): Derksen-Jeandel-Koiran (2005), Kauers-Zimmermann (2008)
 - general: Hrushovski-Ouaknine-Pouly-Worrel (2018)

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We want to compute the algebraic closure of X in \mathbb{C}^4 where

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We compute some powers:

$$M^{0} = \operatorname{diag}(1,1), \qquad M^{1} = \operatorname{diag}(-1,1/5),$$

$$M^{2} = \operatorname{diag}(1,1/25), \qquad M^{3} = \operatorname{diag}(-1,1/(125)),$$

$$M^{-2} = \operatorname{diag}(1,25), \qquad M^{-1} = \operatorname{diag}(-1,5).$$



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Rewrite as:

$$X = \underbrace{\left\{ \operatorname{diag}(1, 5^{2k}) \mid k \in \mathbb{Z} \right\}}_{X_1} \cup \underbrace{\left\{ \operatorname{diag}(-1, 5^{2k+1}) \mid k \in \mathbb{Z} \right\}}_{X_{-1}}.$$



Recall:

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Then we get:

$$\overline{X} = \overline{X_1} \cup \overline{X_{-1}} = \left\{ \begin{pmatrix} x_{11} & x_{12} \\ x_{21} & x_{22} \end{pmatrix} \mid x_{12} = x_{21} = 0, x_{11} = \pm 1, x_{22} \in \mathbb{C} \right\}$$



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where the defining ideal is:

$$I = (x_{11}^2 - 1, x_{12}, x_{21})$$
$$\subseteq \mathbb{C}[x_{11}, x_{12}, x_{21}, x_{22}]$$



- $M \in \operatorname{Mat}_n(\mathbb{C})$
- $G = \langle \lambda \in \mathbb{C}^* \mid \ker(M \lambda \operatorname{Id}_n) \neq 0 \rangle \cong G_{\operatorname{tor}} \oplus \mathbb{Z}^{\operatorname{rk}(G)}$
- $X_{>0}$ semigroup generated by M

$$X_{>0} = \left\{ M^k \mid k \text{ positive integer} \right\}$$

• X - group generated by $M \in \operatorname{GL}_n(\mathbb{C})$

$$X = \langle M \rangle = \left\{ M^k \mid k \text{ integer} \right\}$$

• \overline{S} - Zariski closure of $S \subseteq Mat_n(\mathbb{C})$ in \mathbb{C}^{n^2}

Our goal is to determine algebro-geometric properties of \overline{X} or $\overline{X_{>0}}$.



Lemma

If M is invertible, then $\overline{X} = \overline{X_{>0}}$.

<u>Recall</u>: our warming-up example with M = diag(-1, 1/5).



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For M invertible, write $M\sim M_sM_u$ with M_s diagonal and M_u unipotent (Jordan normal form). Define then

$$X_s = \overline{\{M_s^k \mid k \in \mathbb{Z}\}}$$
 and $X_u = \overline{\{M_u^k \mid k \in \mathbb{Z}\}}$

Lemma

If M is invertible, then $\dim \overline{X} = \dim X_s + \dim X_u$ and $\operatorname{irr}(\overline{X}) = \operatorname{irr}(X_s)$.

Theorem

Assume $M \in GL_n(\mathbb{C})$. Then $irr(\overline{X}) = |G_{tor}|$ and each irreducible component of \overline{X} is a toric variety of dimension

$$\dim \overline{X} = \begin{cases} \operatorname{rk}(G) & \text{if } M \text{ is diagonalizable}, \\ \operatorname{rk}(G) + 1 & \text{otherwise}. \end{cases}$$

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Example

Let us look again at the matrix

$$M = \begin{pmatrix} -1 & 0\\ 0 & 1/5 \end{pmatrix}.$$

Then M is diagonalizable and $G = \langle -1, 1/5 \rangle \cong \mathbb{Z}/(2) \oplus \mathbb{Z}$. We recover our two lines in \mathbb{C}^4 .

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If M = diag(3, 1/3, 9), then $G = \langle 3, 1/3, 9 \rangle = \langle 3 \rangle \cong \mathbb{Z}$.

- Get matrix of exponents: $A = (1 1 2) \in \operatorname{Mat}_{\operatorname{rk}(G) \times n}(\mathbb{C}).$
- Compute kernel: $\ker_{\mathbb{Z}}(A) = \mathbb{Z}(1,1,0) \oplus \mathbb{Z}(-2,0,1).$
- Derive equations: xy = 1 and $x^2 = z$.

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2. $M = M_s \Rightarrow \overline{X}$ has $|G_{tor}|$ toric comp.s with dim = rk(G). For $q = |G_{tor}|$ define $X_i = \{M^{kq+i} \mid k \in \mathbb{Z}\}$. Then $\overline{X} = \overline{X_0} \cup \ldots \cup \overline{X_{q-1}}$.

Conclude by observing

$$X_0 \longleftrightarrow M^q \longleftrightarrow G^q = \langle x^q \mid x \in G \rangle$$
 torsion-free.

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Consider the matrix

$$M = \begin{pmatrix} 1 & 1 & 0 \\ 0 & 1 & 1 \\ 0 & 0 & 1 \end{pmatrix} \rightsquigarrow M^{\alpha} = \begin{pmatrix} 1 & \alpha & \alpha(\alpha - 1)/2 \\ 0 & 1 & \alpha \\ 0 & 0 & 1 \end{pmatrix}$$

satisfying $x_{ii} = 1, x_{12} = x_{23}, x_{i>j} = 0.$

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$$\mathbb{C} \to \mathbb{C}^3$$
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4. Conclude using lemmas.



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Example

Let d be a non-negative integer and define

$$M = \begin{pmatrix} 2 & 0\\ 0 & 2^d \end{pmatrix} \in \mathbb{C}^2.$$

Then \overline{X} is a smooth irreducible affine curve of degree d and equation $y = x^d$. It is rational and, when $d \ge 3$, singular at infinity.



Example

Let $M \in \operatorname{Mat}_n(\mathbb{C})$ be defined by

$$M = \begin{pmatrix} 0 & 1 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 2 \end{pmatrix} \rightsquigarrow M^2 = \begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 4 \end{pmatrix} = \operatorname{diag}(0, 0, 4).$$



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Then $X_{>0} = \{M\} \stackrel{.}{\cup} \{\operatorname{diag}(0,0,2^k) \mid k \ge 2\}.$



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Then $X_{>0} = \{M\} \stackrel{\cdot}{\cup} \{\operatorname{diag}(0,0,2^k) \mid k \ge 2\}$. Since the closure of $\{\operatorname{diag}(0,0,2^k) \mid k \ge 2\}$ has dimension 1, we get that

 $\overline{X_{>0}} = \{M\} \ \cup \ \{\operatorname{diag}(0,0,z) \mid z \in \mathbb{C}\}$

and $\overline{X_{>0}}$ is the disjoint union of a point and a line.



 We have implemented part of our results in SageMath: with input M ∈ GL_n(ℂ) our algorithm returns the equations of X_s.



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- In some cases, our results suffice also to deal with X non-cyclic. In general, we derive lower bounds.

Example

Define $X = \langle A, B \rangle$ where

$$A = \begin{pmatrix} 2 & 0 \\ 0 & 1 \end{pmatrix} \text{ and } B = \begin{pmatrix} 1 & 0 \\ 0 & 3 \end{pmatrix}.$$

Then X contains as a subgroup $Y = \left\{ \operatorname{diag}(2^h, 3^h) \mid h \in \mathbb{Z} \right\}$ and so \overline{X} is a plane in \mathbb{C}^4 .



- Paul Görlach has shown in his PhD thesis (2020+) that, if X is generated by diagonal matrices, then the irreducible components of \overline{X} are toric. Always true if X abelian?
- Work (2020+) of Majumandar, Ouaknine, Pouly, Worrel shows that toric varieties pop up as invariants also in the conext of linear hybrid automata. Properties?



- What happens if X is non-abelian?
- What happens over arbitrary fields?

